

## A new Data-Driven Approach for Comparative Assessment of **Baseline Load Profiles Supporting the Planning of Future Charging Infrastructure**

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#### **ABSTRACT**

In order to achieve the worldwide set ambitious climate goals, the identification and characterization of flexibility in city districts can reduce grid loads and avoid grid congestion. Unlike other flexibility indicators in the literature, the present paper introduces a new flexibility indicator that uses a data-driven approach to determine flexibility from actual measured load profiles. We present this new indicator by considering flexibility in the context of planning charging infrastructure with a valley filling approach. For this use case, we introduce a data-analysis workflow to apply the presented flexibility indicator. The described data-analysis workflow is applied to data from a real-world city district.

Based on the results from the real-world data, we show that the highest peak load and the least flexible peak are not always identical. Therefore, it is not sufficient to consider only the highest peak loads to adequately describe flexibility. Furthermore, we discuss that additional flexibility can be used as another degree of freedom to optimize the charging power or the charging duration. In the presented real-world data, we show that the maximum required charging power is determined by the most inflexible peak and can be the same or smaller for all peaks with a higher flexibility. Moreover, we highlight the difference between considering buildings individually and combining them as a district.

#### **CCS CONCEPTS**

• Hardware → Smart grid; • Mathematics of computing → Time series analysis; • Information systems  $\rightarrow$  Data analytics.

#### **KEYWORDS**

flexibility, city district, charging infrastructure planning, valley filling, real-world data

#### **ACM Reference Format:**

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#### 1 INTRODUCTION

Governments around the world set ambitious goals on carbon reduction to combat climate change. For example, the German federal government aims at reducing carbon emissions by 55 % until the year 2030 compared to 1990 [25]. Worldwide, the residential sector contributes 20 %, the service sector 14 % and the transport sector 35 % to the primary energy consumption [6]. Since those sectors all come together in city districts, city districts play a significant role in the transformation of the energy sector.

In view of advancing energy transition, the exploitation of flexibility potential in city districts becomes crucial, in order to reduce grid loads and avoid grid congestions [35]. To identify and quantify the flexibility potential, suitable methodology and flexibility indicators are needed. A variety of papers like [13, 18, 21, 22, 24] and [4, 5, 16] address the description and quantification of flexibility. Furthermore, recently published meta analyses like [20], [19] or [10] give a holistic overview of all kinds of different methods and indicators describing flexibility. Those indicators, for example, consider the spread of key figures, e.g. emissions or costs, between low and high load periods (see flexibility factor in [10]), the selfsufficiency and self-consumption indicator [10] or the capacity of controllable loads, in order to reduce energy consumption in case of a demand response measure [10].

As those papers present a high number of different indicators, it can be concluded that no single indicator fits all applications and research questions. Papers like [3] show that flexibility is always in some form linked to physical devices, that can either reduce or shift their demand in time. As governments accelerate the transition towards a sustainable transport system, electric vehicles (EVs) and charging infrastructure (CI) become increasingly significant devices for flexibility provision. For example, according to the 'Klimaschutzprogramm 2030' [25] of the German federal state, one million charging points shall be installed until the year 2030 from which, less than 7 % was reached in September 2022 [7].

With those high numbers of CI still in the planning phase, there is an urgent need for flexibility indicators, that do not only describe the operation but also help in the planning phase of new CI. However, most flexibility indicators are centered around the building heating, ventilation, and air conditioning (HVAC) sphere and are not applicable on CI. Further, these flexibility indicators are not primarily based on measurement data and require detailed modelling [10].

Paper that cover planning of CI like [13, 22, 28, 31] all approach the planning from the perspective of expected charging behavior, considering different vehicle types and usage characteristics and concluding the required size of CI to fulfill this demand. This assumes that the on-site conditions in a city are ideally adaptable to the identified charging demand. In reality, however, CI is part of the superordinate, already existing city infrastructure (like parking spaces or the distribution grid with other existing energy consumers). Therefore, a suitable flexibility indicator needs to take the characteristics of the existing superordinate infrastructure into account.

The relevant aspects of the superordinate infrastructure are to some degree of physical and to some of legal nature. From the hierarchical perspective, a city consists of different districts, that themselves consist of different buildings (see Figure 1). From a legal standpoint, the connection point between the building and the superordinate grid, i.e. the grid connection point (GCP) is of interest (e.g. 'Kundenanlage' in the German law [8]). The GCP can be associated with a single building or aggregate multiple buildings in other cases (see Figure 1). In the private grid, subordinate to the GCP, energy can be exchanged without the supplier being regulated as a utility company, leading to reduced costs and bureaucracy [8]. Also, the energy billing is carried out on the load profile of each GCP individually [9]. While papers like [27], [23] or [36] describe the demand for flexibility in the energy market and how to quantify flexibility of existing flexible plants, we focus on characterizing the potential for future supply through future CI. Our approach makes different GCPs comparable. This information can then be used to be matched against the flexibility needs of the market and the superordinate grids to make a planning decision.

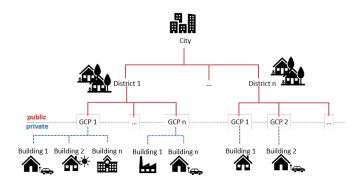


Figure 1: Hierarchy of superordinate infrastructure: Multiple buildings at one GCP (left) or one building only per GCP and coupling of buildings only through public grid (right)

Therefore, suppliers of local renewable energy and operators of the private grid in one GCPs only optimize the internal consumption inside their single GCP and do not consider the other GCPs in the district. Therefore, a suitable flexibility indicator needs to make the different GCPs comparable. Furthermore, research like [21] or [26] suggest, that aggregation of buildings to a district leads to advantages in flexibility and grid support. Since the aggregation at district level faces multiple legal problems in the current system (e.g., for Germany see [12]), the advantages of combining multiple GCPs to a district also need to be critically examined.

Besides grid congestion, cost reduction is a main motive for exploiting flexibility [10]. In countries like Germany, billing periods

can not only be on a yearly, but also on a monthly basis, according to StromNEV § 19 [9]. The charged prices are composed of an energy related share ( $\mathfrak{e}/kWh$ ) and a power related share ( $\mathfrak{e}/kW$ ). A monthly billing period, in this case, means, that the power component is charged for each month individually on its highest monthly consumption peak. Therefore, a suitable flexibility indicator should also be able to characterize flexibility regarding monthly power peaks.

To avoid new and even higher peaks, charging needs to take place during off-peak times. In the context of load shaping approaches as defined in [10], this means a valley filling approach. Valley filling is widely examined in literature [1, 2, 11, 15, 17, 30, 32–34]. Those works all present different algorithm and control strategies, like decentralized coordination [32, 33], control through price signals [1, 15, 17, 33] or further grid friendly behavior, like reduced power ramps [30, 33] or the consideration of the limits of the local power transformer or a local grid [11, 15].

However, [1, 2, 11, 14, 15, 17, 30, 32–34] all target at optimizing the operation of CI during everyday production usage. Therefore, they do not focus on providing indicators that quantify the flexibility in a way to make GCPs comparable to support the planning phase of new CI.

Since, as [10] points out, valley filling aims at increasing the consumption in off-peak hours and those are characterized by a baseline load profile<sup>1</sup> the assumed baseline load profile is of high relevance. The baseline load profile in [33] is based on data of a Californian system operator, [34] uses measured data from a transformer in Shenzhen and [11] utilizes the load profile of the IEEE 14-bus system. However, only single load profiles with a limited time range are used by [11, 33, 34] and a comparison of multiple load profiles over a whole year is missing. In other paper like [1, 2, 15, 32] it is not even clear, what the baseline load profile is based on. A study and comparison of several measured real-world baseline load profiles and their difference or suitability for valley filling is missing. To conclude, a data-driven approach for quantifying CI flexibility of measured baseline load profiles of existing buildings or districts regarding the suitability for valley filling is needed.

When considering a data-driven approach, it should be based on features used for flexibility description, like proposed in [18]. One main feature is the time for which a flexibility source is available [18]. For example, a charging session of an EV lasts from 20 min to 6 h depending on the location type [13]. The limitation on available charging power is highest around peaks of the baseline load profile. Therefore, the flexibility indicator must be able to reflect the limited availability in the surroundings of a load peak.

To sum up, a suitable flexibility indicator needs to consider characteristics of charging infrastructure like limited availability of vehicles and limited charging power. Furthermore, it must support the planning phase of new CI. In addition, the flexibility indicator should make different GCPs comparable. And lastly, it needs to consider monthly and yearly consumption peaks and be extractable from existing baseline load profiles without further assumptions needed for vehicle or user behavior. Instead, it should only quantify

 $<sup>^{\</sup>rm 1}{\rm Baseline}$  meaning the measured load profile under current consumption and behavioral conditions without the newly planned CI.

the suitability of a GCP for the future installation of grid friendly CI (that does not produce additional peaks besides the existing ones) through a data-analysis of baseline load profiles.

The remainder of the paper is organized as follows: Section 2 presents our methodology to calculate the flexibility indicator. In section 3, we present a real-world district that contains four different GCPs. In section 4, we discuss the application of our methodology on the real-world data. Additionally, subsection 4.2 presents the comparison of the different GCPs, subsection 4.3 examines the correlation of flexibility and peak height, and subsection 4.4 discusses flexibility on a district level compared to each GCP individually. Section 5 closes the present article, giving relevant conclusions and an outlook for future work.

#### 2 METHODOLOGY

In section 2 we present the data-driven approach, fulfilling the requirements laid out in section 1. The full workflow of the data-analysis process is depicted in Figure 2. Since the approach is based on analyzing a baseline load profile regarding power peaks, a first step is to acquire and prepare the baseline load profiles of each GCP (subsection 2.1) and to identify the different types of peaks (subsection 2.2). In the next step, the flexibility indicator is defined and calculated for each GCP (subsection 2.3). Afterward, a filtering step is included to select only the relevant peaks of each GCP for further analysis and comparison (subsection 2.4). Furthermore, the power limitation aspect of CI is considered in subsection 2.5. The obtained results are then used to compare the different GCPs in order to answer the further research questions posed in section 1.

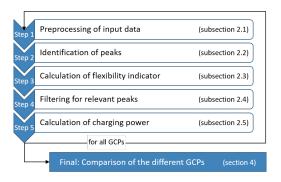


Figure 2: Overview of data-analysis workflow for all GCPs individually with a final comparison of the different GCPs

#### 2.1 Preprocessing of input data

When considering preprocessing, features of interest are: time zone, temporal resolution, value resolution and time frame of available data. The resolution is relevant for both the temporal and the value axis, since measured values are usually both time discrete and value discrete. The temporal resolution ( $\Delta t$ ) is assumed as 15 min equidistant. The value resolution ( $\Delta p$ ) depends on the quality of the power measurement and can greatly influence the results. For example, at  $\Delta p$ , it might appear that multiple 15 min power values have the same magnitude, resulting in multiple peaks that appear to be equally important but exhibit potentially quite different load

profile shapes before and after the peak. Because billing of peaks is carried out on a time frame of a month or a year, the available data needs to cover at least one year per GCP. Further research is needed to investigate, whether the relevant key figures could also be extrapolated on a data basis of a smaller time frame.

## 2.2 Identification of peaks

Firstly, all potentially relevant peak data points need to be identified. These are power maxima at the level:

- $p_{qy}$ : global year (calendar feature)
- *p<sub>qm</sub>*: global month (calendar feature)
- p<sub>l</sub>: local (in given number of neighboring data points)

The set of local maxima includes the monthly maxima which include the yearly maxima:

$$p_{gy} \subset p_{gm} \subset p_l \tag{1}$$

The yearly maxima  $(p_{gy})$  and monthly maxima  $(p_{gm})$  are defined as the highest 15 min power value in a given yearly or monthly time frame. If the power value resolution is low in relation to the absolute power level, more than one data point may have the same global power level in the given time frame. In this case, both data points are classified as yearly/monthly peaks.

The local maxima are identified by finding the highest (or equal) power value in a given surrounding of each data point (*order*) for the entire load profile. With a 15 min temporal resolution, a single day has 96 data points that result in an order of 48. This makes it possible to identify approximately one local maximum per day without being limited through calendar features (e.g., a maximum right around midnight, that would be counted twice if identified by the day as a calendar feature).

#### 2.3 Calculation of flexibility indicator

As discussed in section 1, the flexibility is characterized by the baseline load profile during a certain time frame  $t_f$  around any peaks specified in subsection 2.2. The main function of the time frame  $t_f$  is to have a comparable metric for each load profile. The size of the time frame influences the expressiveness of the flexibility indicator. Regarding CI, the longest expected charging duration is 6 h (see section 1). Therefore, it can be assumed that  $t_f$  of 6 h is the best suite as a starting point for this paper. A  $t_f$  of 6 h leads to an evaluated range from -3 h to 3 h around each peak time  $(t_l)$ . With a  $\Delta t = 15$  min resolution, that leads to 12 values before and after  $t_l$ , resulting in:  $t_f = \{t_l + k \cdot \Delta t | k \in [-12, 12] \cap \mathbb{Z}\}$ .

The flexibility indicator is calculated for every local peak. In a first step, the flexible energy around each peak  $(e_{l,flex})$  is calculated as:

$$e_{l,flex} = \sum_{i=t_l-12}^{t_l+12} (p_g - p_i) \cdot \Delta t$$
 (2)

Figure 3 shows the baseline load profile (gray) and for the relevant time frame  $t_f$  in the surrounding of  $t_l$  also  $e_{l,flex}$  in red.

The global peak power  $p_g$  can either be the yearly maximum  $p_{gy}$  or the monthly maximum,  $p_{gm}$  depending on the billing system for the individual GCP. To compare also the suitability of the two different billing methods for the different GCPs, both, the monthly and the yearly billing system are evaluated in this paper. The value of  $e_{l,flex}$  is calculated for every local power maximum  $(p_l)$  and

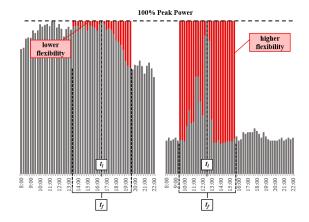


Figure 3: Examples for one peak with low flexibility (left) and one peak with high flexibility (right)

therefore, for each timestamp,  $t_l$  of a local power maximum. We define the inflexible energy  $e_{l,fix}$  by:

$$e_{l,fix} = \sum_{i=t_1-12}^{t_l+12} p_i \cdot \Delta t \tag{3}$$

The flexibility indicator f is then defined as the share of flexible energy  $e_{l,flex}$  of the overall energy  $(e_{l,flex} + e_{l,fix})$  in a given time frame  $t_f$ . It ranges from 0.96 as an ideal peak with the highest flexibility to zero as the worst peak with the lowest flexibility<sup>2</sup>:

$$f = \frac{e_{l,flex}}{(e_{l,flex} + e_{l,fix})} \in [0, 0.96]$$
 (4)

As mentioned, both billing methods ( $p_{gy}$  and  $p_{gm}$ ) are evaluated, leading to  $f_y$  (yearly billing period) and  $f_m$  (monthly billing period).

#### 2.4 Filtering for relevant peaks

The peak with the lowest flexibility  $f_{min}$  limits and characterizes the whole GCP. In addition, the second and third most inflexible peaks characterize the GCP. However, below a certain threshold, the peaks are too low to be representative of the characteristics of the GCP. This threshold is defined using normalizes local peaks  $p_{n,l} = p_l/p_{gy}$  (yearly) and  $p_{n,l} = p_l/p_{gm}$  (monthly) and the characteristic flexibility  $f_{min}$  (min( $f_y$ ) or min( $f_m$ ) correspondingly) as:

if 
$$(p_{n,l} + f_{min} > 1)$$
 then  $\rightarrow$  relevant (5)

This assumption filters out all peaks, allowing for permanent charging with average charging power without the need for load shifting.  $f_{min}$  also depends on the billing period as described in subsection 2.3. The rating is therefore also carried out on a yearly and a monthly basis.

## 2.5 Calculation of charging power

Subsection 2.4 discusses the filtering for relevant peaks. The peaks that required some sort of load shifting were identified as the relevant peaks. However, as the other relevant peaks all show a higher flexibility than  $f_{min}$ , they exhibit a certain surplus of flexibility and therefore a further degree of freedom. Figure 4 shows two different ways to use the surplus flexibility: for charging power optimization or for charging time optimization. Due to costs, it is of interest to minimize the charging power needed to exploit the maximum flexibility. Consequently, the minimum required charging power is calculated as a further indicator to characterize the GCP.

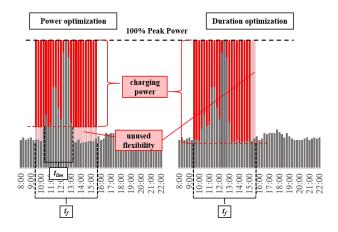


Figure 4: Example for utilization of flexibility with charging limit: Utilization of flexibility for power optimization (left) and for charging duration optimization (right)

The following paragraph describes the algorithm to calculate the minimal required charging power (see Algorithm 1). The reference is the energy that can be charged at the most inflexible peak ( $e_{min} =$  $e_{l flex}(f_{min})$ ). At least this amount should be chargeable at all other peaks as well. Therefore, during the calculation, the charging power  $p_{cha}$  is gradually increased, until the integral over all time steps  $(t \in t_f)$  matches the energy chargeable at the most inflexible peak. For timestamps, where a charging power limitation is needed  $(t \in t_{lim})$ , the maximum power reserve until the peak power is used for charging. We use the normalized (on the year peak) baseline load profile  $p_n[t]$ . The charging power during  $t_{lim}$  is then given as (1  $p_n[t]$ ). For the remaining timestamps ( $t \in t_{unlim}$ ), charging with the maximum charging power  $p_{cha}$  is assumed. The algorithm tries to find a data point with the next higher charging power  $p_{cha,tmp}$ until the required energy  $e_{min}$  is met. Since  $\Delta t$  and  $t_f$  are fixed values for all peaks, and  $\Delta e = p \cdot \Delta t$ , the term  $\Delta t$  can be set to one and the energy can be determined by  $e = \sum \Delta e = \sum p$  as a sum of the powers of the individual time intervals. The charged energy  $e_{cha}$ consists of a part during limited  $e_{lim}$  and a part during unlimited  $e_{unlim}$  charging. The charging power during the unlimited time per definition needs to be higher or the same as the power during the limited times. Therefore, if the energy requirement is fulfilled, the maximum charging power can be calculated as the energy charged during unlimited charging  $(e_{unlim} = e_{min} - e_{lim})$  divided by the number of time steps of unlimited charging (len $(t_{unlim})$ ).

 $<sup>^2</sup>$ For the  $t_f$  used in this paper, the best case are 24  $\Delta t$  with 100 %  $e_{l,flex}$  and the peak  $\Delta t$  with 100 %  $e_{l,fix}$  leading to f=24/25=0.96.

#### Algorithm 1 Identifying maximum required charging power

```
e_{min} \leftarrow len(\mathbf{t_f}) \cdot \min(\mathbf{fy})
while e_{cha} < e_{min} do
   \mathbf{p_{unlim}} \leftarrow \mathbf{p_n} \text{ where } p_n < (1 - p_{cha})
   p_{cha,tmp} \leftarrow (1 - \max(\mathbf{p_{unlim}}))
   for t \in t_f do
       if t \in t_{lim} then
           e_{lim} \leftarrow e_{lim} + (1 - \mathbf{p_n}[t])
       else if t \in t_{unlim} then
           e_{unlim} \leftarrow e_{unlim} + (1 - p_{cha,tmp})
       end if
   end for
   e_{cha,tmp} \leftarrow e_{lim} + e_{unlim}
   if e_{cha,tmp} < e_{min} then
       p_{cha} \leftarrow p_{cha,tmp}
       e_{cha} \leftarrow e_{cha,tmp}
   else if e_{cha,tmp} >= e_{min} then
       p_{cha} = (e_{min} - e_{lim})/len(\mathbf{t_{unlim}})
       break
   end if
end while
```

#### 3 REAL-WORLD DISTRICT AND DATA BASE

In section 3, we present the real-world district in the city of Karlsruhe, Germany, and present the data base.

#### 3.1 Real-world district

The district is of a mixed residential-commercial type. Regarding charging profiles, charging at work is present as well as the charging of car-sharing vehicles and charging by residents. Since it is an urban district, the potential for further renewable energy generation is limited. The district consists of four GCPs with a multitude of buildings subordinate to each GCP (see Figure 5; compare Figure 1). The GCPs are coupled through the public 20 kV grid. Regarding the construction year, the district is quite heterogeneous. It reaches from buildings constructed less than 5 years ago to ones constructed more than 120 years ago.



Figure 5: Buildings of the four GCPs in the real-world district in Karlsruhe, Germany [29]

As mentioned in section 1, the GCP is a relevant billing boundary. Energy supplier within the GCPs are not regulated as utility companies. Furthermore, within the GCPs in this specific district, local generation and consumption is further subsidized<sup>3</sup>. The advantages of reduced regulation and subsidies are omitted, when utilizing the public grid for energy exchange. Therefore, the advantages of considering the whole district versus the single GCPs need to be critically examined in subsection 4.4.

#### 3.2 Data base

The real-world load profiles used in the present paper were measured by the utility company for billing purposes. The temporal resolution (compare subsection 2.1) of the load profiles is equidistant 15 min and the data is available for the whole year of 2021. All load profiles were converted in UTC with the start timestamps of each period and the power consumption for each GCP. For plots of the load profiles, see Appendix A.

As mentioned in subsection 2.1 the value resolution  $\Delta p$  significantly influences the number of identified local peaks  $p_I$ . The  $p_I$ values were obtained following the method described in subsection 2.2 with an order of 48. The  $\Delta p$  of the real-world load profiles ranges from  $0.001\,\%$  to  $2.128\,\%$  given in percent of the peak power  $p_{qy}$  as shown in Table 1. GCPs with a lower value resolution (higher  $\Delta p$ ) present a significantly higher number of  $p_l$  (compared Table 1). For example, for GCP 2, 1372  $p_I$  were identified instead of the expected average of 365 per year (resp. 366 in 2021 due to leap year). The number of additionally identified  $p_l$  can be characterized by the occurrence of adjacent maxima or several maxima in one calendar day. Of GCP 2's total of 1372  $p_l$ , 670 have directly adjacent  $p_l$  with the same value. In 1013 cases of the 1372  $p_I$ , more than one  $p_I$  per calendar day was identified due to an indistinguishable peak level. However, since they do represent real world power maxima and it is not possible to extract a more precise peak value, all data points at the peak level were treated as equally relevant in this work. In future work, other methods like filtering according to flexibility indicator or peak slope could be examined.

Table 1: Lower value resolution  $\Delta p$  leads to a lower number of distinguishable peak power levels and multiple values, either directly neighboring or within the same day exhibiting an identical peak level and therefore leads to more peak values (number of identified  $p_l$ ) than the ideal 365-366 per year

	GCP 1	GCP 2	GCP 3	GCP 4
$(\Delta p/p_{gy})$	0.001 %	2.128 %	0.049%	0.901 %
number of identified lo-	375	1372	430	501
cal peaks <i>p</i> <sub>l</sub>				
number of peaks with	22	670	74	110
immediate neighbor at				
same power level				
number of additional	22	1013	117	153
peaks per calendar day				

<sup>&</sup>lt;sup>3</sup> Mieterstromzuschlag' according to EEG 2021 §21 3.2 and reduced grid fees according to StromNEV §18 1.1.

#### 4 RESULTS AND DISCUSSION

In section 4, we discuss the results obtained from applying the methodology presented in section 2 to the data base presented in section 3.

### 4.1 Application of data-analysis workflow

Since the data-analysis workflow has already been described in detail in section 2, only the specifics of the results are discussed in the following. Besides the quality of the data base, which was described in subsection 3.2, the results of the filtering process and the determined flexibility indicators are the main factors to be examined.

Peaks are in their nature outliers and extreme values. In average, only 1.93 % of all peaks of the real-world validation dataset are relevant for flexibility characterization on a yearly basis. Significantly more data points, 29 % of all peaks, characterize the monthly flexibility (compare Table 2). Future work also needs to examine the sensitivity of the percentage of relevant peaks toward  $t_f$  (that was chosen as a 6 h time frame in this work, see subsection 2.3). The other results of the analysis workflow are presented in the

Table 2: In contrast to  $p_l$ , the absolute number of relevant peaks on a yearly basis  $(f_y)$  or a monthly basis  $(f_m)$  is not significantly influenced by  $\Delta p$  for the data basis used in this work. The additional peaks are irrelevant for the characterization of the GCP (see subsection 2.4)

	GCP 1	GCP 2	GCP 3	GCP 4
number of identified $p_l$	375	1372	430	501
relevant on yearly basis	2	15	9	20
relevant on monthly basis	112	128	221	129
irrelevant	263	1244	209	372

following directly in the form of a comparison of the four GCPs.

# 4.2 Comparing the data-analysis results for the four GCPs

The monthly and yearly flexibility show the same characteristics of the GCPs for the given dataset. Meaning, the higher the flexibility on a yearly basis, the higher it is also on a monthly basis (see Table 3 and Figure 6).

Table 3: Characteristic flexibility  $f_{min}$  and corresponding normalized power  $p_n$ 

	GCP 1	GCP 2	GCP 3	GCP 4
$f_{min,y}$ $p_{n,y}$ at $f_{min,y}$	0.14	0.07	0.14	0.13
	1.000	0.957	1.000	0.964
mean $f_{min,m}$	0.44	0.08	0.23	0.16
mean $p_{n,m}$ at $f_{min,m}$	0.959	0.998	0.893	0.953

GCP 1 and GCP 3 exhibit the highest and GCP 2 the lowest flexibility. This indicates that information on the flexibility of different

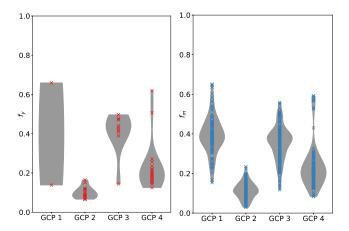


Figure 6: Comparison of  $f_y$  and  $f_m$  show similar tendencies regarding the minimum exhibited flexibility and the flexibility distribution for all GCPs

GCPs could be extracted even of less than a year of data. Future research should further examine this relation and take an in-depth look at monthly billing systems and conduct a more detailed analysis of single months.

On a yearly basis, one single peak data point may exhibit a significantly lower flexibility than all other relevant peaks. In the presented data, this was the case for GCP 1 and GCP 3 (see Figure 6). In those cases, allowing underfulfillment for a single peak could significantly increase the flexibility. The CI could be planned according to the next higher flexibility by only under fulfilling a single 6 h time frame. The presented approach explicitly does not have the aim to describe operating strategies or control algorithms and should only support the planning of new CI. However, including analysis of the sensitivity towards underfulfillment could lead to further understanding and better planning in future works.

As shown in Table 4 and Figure 7, to achieve the flexibility displayed in Table 3 at some time steps, the charging power needs to be higher than the mean value to compensate the missing energy of reduced charging periods around the peaks. At all four GCPs the maximum charging power is reached at the most inflexible peak. In average, more than the double (2.2 times) of the mean charging power is needed to achieve the before mentioned flexibility. While in average a power of 11.83 % of the peak consumption in CI can be installed, some GCPs (GCP1 and GCP 3) allow significantly higher charging power than the others.

Table 4: Charging power mean and max values

values as % of $p_{gy}$	GCP 1	GCP 2	GCP 3	GCP 4
worst case max $p_c$ optimal max $p_c$	95.6 % 37.3 %	40.4 % 8.5 %	60.5 % 33.3 %	80.2 % 28.8 %
$\frac{\text{mean } p_c}{}$	13.8 %	6.6 %	14.4 %	12.5 %
CI oversizing reg. mean	2.7	1.3	2.3	2.3

Figure 7 shows the required charging power in relation to the available flexibility. The displayed 'worst case' means the maximum charging power in  $t_f$  is used, meaning charging at a total power consumption of  $p_{gy}$  for any time, charging is active and only stopping, if the energy requirement is met or the power needs to be reduced due to a peak. In the 'optimal case', the charging power is at most the highest charging power from the most inflexible peak.

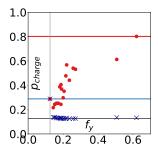


Figure 7: The most inflexible peak determines the maximum charging power, as shown here for GCP 4 (for all GCPs see Appendix C). In the unoptimized case (red o), higher charging powers occur at all peaks exhibiting greater flexibility. The excess flexibility can be used to reduce the charging power (blue x) down to the mean charging power (black line).

The charging power can in average be chosen more than 60 % lower when exploiting the surplus flexibility than in the unoptimized case. Still, the installed charging power needs to be about 2.2 times higher than the average charging power to take advantage of the flexibility potential. The mean proposed charging power lies at 11.83 % of the peak power for the sum of the GCPs (see Table 4). The oversizing of power is characteristic of all plants with flexibility. Otherwise, flexibility provision would not be possible at all. A big advantage of CI is that oversizing is possible at low cost, since in the case discussed it is not necessary to reinforce the supply line to the GCP or the transformer, since new peaks are prevented. Only the plug, and therefore the charging point and the car, have to be able to handle correspondingly higher power.

Since the charging power can be reduced significantly below the charging power from the most inflexible peak, not even all flexibility is used for charging power optimization. This still leaves a margin for safety or other purposes.

#### 4.3 Correlation of flexibility and peak power

Among other things, it was noted in subsection 4.2 that the peak with the highest power peak is not necessarily identical with the most inflexible peak (for example see Figure 8. This finding is examined in more detail in the following.

As shown in Table 5 and Figure 9, peak power and f are strongly negatively correlated. This correlation is statistically significant (p-value lower than 5 %) for the unfiltered values on a yearly and monthly basis and the filtered values on a monthly basis, see Table 5). However, this is not true for the yearly basis due to some short but high peaks. Because of their shortness, those high peaks also exhibit a high flexibility indicator. And because of the reduced number of relevant data points for the yearly basis, those outliers

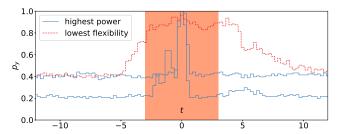


Figure 8: For GCP 4 the peak with the highest power is not the one with the lowest flexibility (all GCPs, see Appendix C)

have a relevant impact. Therefore, a key finding is, that the highest peak cannot be assumed to also be the most inflexible one.

Table 5: On a monthly basis, the peak height and flexibility show a statistically significant negative correlation for all GCPs. On a yearly basis, GCP 1 and GCP 2 show no statistically significant correlation, GCP 3 shows a statistically significant negative and GCP 4 a statistically significant positive correlation

		GCP 1	GCP 2	GCP 3	GCP 4
fy (filtered)	PCC	-1.00	0.15	-0.92	0.64
	p-value	1	0.59	0.00038	0.0026
fm (filtered)	PCC	-0.55	-0.82	-0.55	-0.82
	p-value	3.5e-10	6.6e-32	3.5e-19	1.6e-32

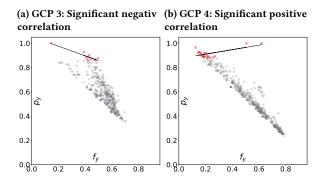


Figure 9: Two examples of the correlation of  $p_y$  and  $f_y$  of filtered values (red x) that can be significantly different for different GCPs (for a complete overview, see Appendix B)

Table 3 shows the peaks with the lowest flexibility. On a yearly basis, those occur at peaks with a proportion of 95.7 % to 100 % of the yearly peak value. In six out of eight of the combinations of GCPs and billing methods, the lowest flexibility does not correlate with the highest peak. On a yearly basis, the lowest flexibility occurs in average at a peak with around 98 % of the yearly peak power. This imposes the need to include suitable characterization methods for flexibility for all use cases or data-analysis methods. For example, a

control algorithm for operating a charging infrastructure should not only be based on a peak forecast but also, at least implicitly, include a flexibility forecast. Meaning, the most critical day for an optimization may not be those with the highest predicted peak but those with a slightly lower but for longer time constantly high baseline profile.

## 4.4 Single GCP versus district

As mentioned in section 1, the advantages of combining multiple GCPs to a district need to be critically examined. For this purpose, the flexibility indicator was calculated for three different scenarios (A, B and C). The parameters of interest are the total peak power and the flexibility indicator values.

4.4.1 Scenario A. In the state-of-the-art scenario, billing is carried out for each GCP separately. Therefore, the least flexible peak of each individual GCP is of interest. The relevant baseline load profile in scenario A is the sum of the individual load profiles around these most inflexible peaks. The peak height is defined by the sum of the peak height of allGCPs around these peaks.

4.4.2 Scenario B. In the district scenario, all GCP's baseline load profiles are summed up before applying the analysis workflow. The whole district is thus considered as one large single consumer. Therefore, the flexibility of the district is calculated on the newly formed maxima of the newly calculated load profile. This would require the law to allow billing on a district level. The advantage of district billing in contrast to GCP based billing is the reduction in required peak power. In the real-world data at hand, the district peak is 23.48 % lower than the peak in scenario A (additional plot, see Figure 14). The flexibility in scenario B (0.089), however, is also reduced by almost 25 % compared to scenario A (0.152). The reduction in peak power also led to a reduction in flexibility. Further evaluation is needed to examine, how much the power can be reduced through a district while still keeping the same flexibility as scenario A. It should be examined what the relationship of peak reduction and flexibility provision on a district level looks like.

4.4.3 Scenario C. To bring the reduced peak power and the reduced flexibility in perspective, as a third scenario C, the district is also evaluated with the maximum power of the sum of the GCPs. In the scenario C, the flexibility (0,245) increases by almost 107 % compared to scenario A (0.152). This means, if the same power maxima than in scenario A is assumed, the district outperforms the state-of-the-art. However, if the full peak power reduction potential of 23.48 % should be utilized, the flexibility is also reduced. There appears to be a tradeoff of peak reduction versus flexibility.

Further, since flexibility is always defined relative to the peak, for a fair comparison, also the different absolute peak height should be considered. Therefore, also the comparison of the mean charging power regarding scenario A is included in Figure 10. In the district scenario B, the mean charging power is reduced by more than 40 %. In scenario C the mean charging power is 3.61 times higher than in scenario A. Moreover, the mean available charging power is reduced alongside the peak power. This likewise shows the presumed tradeoff of peak reduction versus flexibility. Data for

additional districts is needed to further examine the relationship of peak reduction and flexibility provision on a district level.

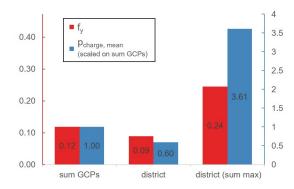


Figure 10: Comparison of characteristic flexibility  $f_y$  and mean charging power  $p_{charge,mean}$  scaled to the current states of separate GCPs

#### 5 CONCLUSION AND OUTLOOK

The present paper shows that flexibility is not a natural inherent and fixed value of an energy system, but rather describes the suitability of an energy system in performing optimal under specific use cases or boundary conditions.

We present a new flexibility indicator that considers characteristics of charging infrastructure, like limited availability of vehicles and limited charging power, which supports the planning phase of new charging infrastructure. Furthermore, we present the whole data-analysis workflow on how to apply the flexibility indicator. We apply the workflow on a data base from a real-world district and examine the monthly and yearly flexibility and compared the different grid connection points of the district.

The data-analysis in the present paper confirms that peak characteristics are highly influencing the suitability for valley filling. We further demonstrate that it is incorrect to assume that the highest peak during a particular time period is also the most inflexible one. The monthly and yearly flexibility show the same characteristics for the given data base. Furthermore, we show that a surplus in flexibility can be utilized to reduce and optimize the maximum required charging power.

Future work should examine the feasibility of extrapolating flexibility on less than one year of data and validate the results on more than one year of data as well as further real-world datasets. Furthermore, different approaches on dealing with lower measurement resolution could be looked into. Moreover, the identified tradeoff of flexibility versus peak reduction on the district level needs to be further investigated, as well as the potential of flexibility increase when allowing underfulfillment of charging demand in a limited time frame. Finally, since we pointed out that the most inflexible peak is not always the one with the highest peak power, this imposes the need to at least implicitly include flexibility in future works on forecasts and optimizations, and it is not sufficient to only use the highest peak power values as key indicators.

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#### **AUTHOR CONTRIBUTIONS**

Author contributions according to Contributor Roles Taxonomy (CRediT, https://www.casrai.org/credit.html): Conceptualization: J.G.; Methodology: J.G.; Software: J.G.; Formal analysis: J.G.; Investigation: J.G.; Data curation: J.G.; Writing - original draft: J.G.; Writing - review and editing: J.G., S.W., V.H.; Visualization: J.G.; Supervision: S.W., V.H.; Project administration: S.W.; Funding acquisition: V.H.

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## A REAL-WORLD BASELINE LOAD PROFILES

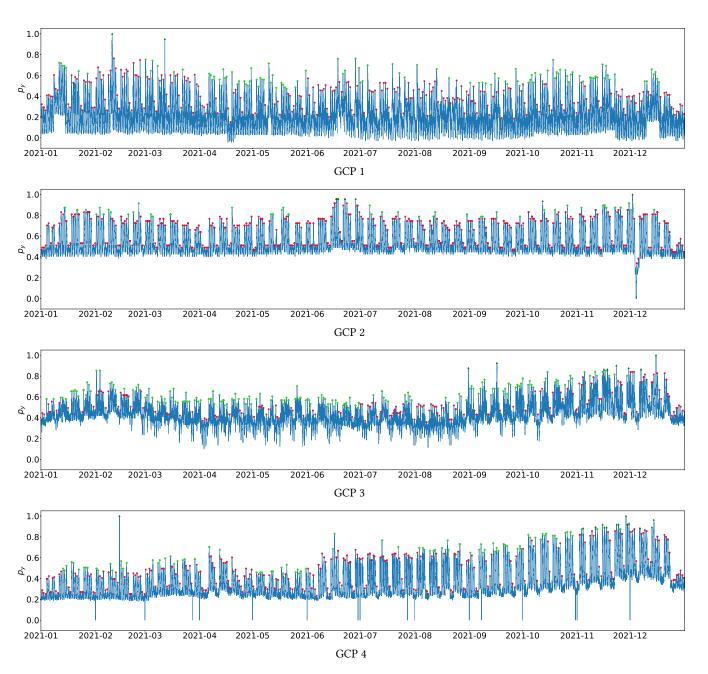


Figure 11: Baseline load profiles of all GCPs

## B CORRELATION OF FLEXIBILITY (f) AND PEAK POWER (p)

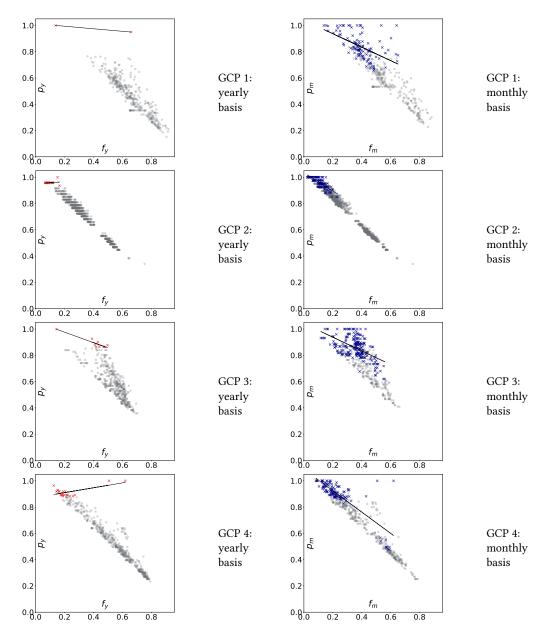


Figure 12: Correlation of flexibility (f) and peak power (p) of all GCPs on a yearly and a monthly basis black lines marking linear regression of correlation of filtered values, x marking relevant and o marking irrelevant peaks

#### C MOST INFLEXIBLE PEAKS AND CHARGING POWER

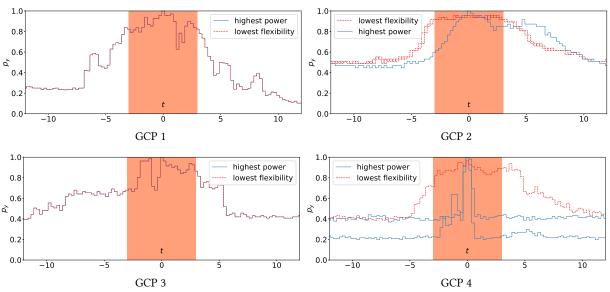


Figure 13: For GCP1 and GCP3 the highest year peak corresponds with the most inflexible peak. Regarding GCP2 and GCP4, the year peak is significantly more flexible, than other peaks

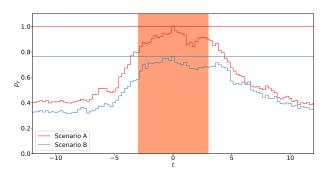


Figure 14: Sum of the most inflexible peaks of all GCPs (sce. A) versus the most inflexible peak of the district profile (sce. B)

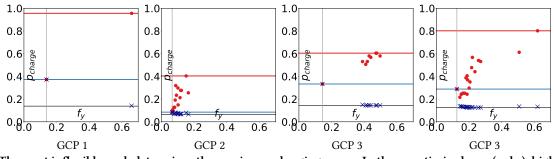


Figure 15: The most inflexible peak determines the maximum charging power. In the unoptimized case (red o), higher charging powers occur at all peaks exhibiting greater flexibility. The excess flexibility can be used to reduce the charging power (blue x) down to the mean charging power (black line).